



Koneru Lakshmaiah Education Foundation

(Category -1, Deemed to be University estd. u/s. 3 of the UGC Act, 1956)

Accredited by NAAC as 'A++' ♦ Approved by AICTE ♦ ISO 21001:2018 Certified
 Campus: Green Fields, Vaddeswaram - 522 302, Guntur District, Andhra Pradesh, INDIA.
 Phone No. +91 8645 - 350 200; www.klef.ac.in; www.klef.edu.in; www.kluniversity.in
 Admin Off: 29-36-38, Museum Road, Governorpet, Vijayawada - 520 002. Ph: +91 - 866 - 3500122, 2576129

Department of Mechanical Engineering

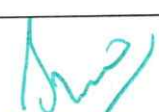
Program: M.Tech-Robotics and Mechatronics

Academic Year :2019-2020


| S.NO. | CourseCode | CourseTitle | CO No. | Description of the Course Outcome |
|-------|------------|----------------------------------|--------|---|
| 1 | 18ME5101 | FUNDAMENTALS OF MECHATRONICS | CO1 | Apply the principles of mechatronics and automation for the development of productive and efficient manufacturing systems. |
| | | | CO2 | Be proficient in the use of Data conversion devices and Microprocessors controllers and select suitable drives |
| | | | CO3 | Be able to analyze mechanisms for industrial applications and Design and analyze Hydraulic systems |
| | | | CO4 | Analyze the Pneumatic systems and understand PID controllers, CNC machines and Industrial Robotics. |
| 2 | 18ME5102 | ADVANCED ENGINEERING MATHEMATICS | CO1 | Perform elementary operations on matrices including determination of rank and inverse, demonstrate mastery in using matrix algebra. |
| | | | CO2 | Interpret and apply differential calculus on problems involving rate of change |
| | | | CO3 | Illustrate the applications of integral calculus in solving problems on area, volume, displacement, work. |
| | | | CO4 | Determine gradient, divergence and curl of vector point functions with their properties |
| 3 | 18ME5103 | SENSORS AND ACTUATORS | CO1 | Identify appropriate sensor for a particular Mechatronic system. |
| | | | CO2 | Understand micro electro mechanical system and its manufacturing methods |
| | | | CO3 | Understand the hydraulic and pneumatic Actuation systems for selection of appropriate actuation method for a particular Mechatronic system. |
| | | | | Understand the electrical actuation |

Dr. A. SKINATH
PROFESSOR & HEAD
 Department of Mechanical Engineering
 KL (Deemed to be University)
 Vaddeswaram - 522 502

| | | | | |
|---|----------|--|-----|--|
| | | | | systems for selection of appropriate |
| | | | CO4 | actuation method for a particular |
| | | | | Mechatronic system. |
| 4 | 18ME5104 | MODELING AND SIMULATION OF MECHATRONIC SYSTEMS | CO1 | Build mathematical models of mechatronic systems comprising combinations of mechanical, electrical, pneumatic/hydraulic and thermal systems |
| | | | CO2 | Analyze systems for their time response to a certain input using transfer function and /or state space approach |
| | | | CO3 | Apply system identification techniques to synthesize system models |
| | | | CO4 | Evaluate time and frequency response of systems and control system design |
| | | | CO5 | Modeling and Simulation of Mechatronic Systems using MATLAB/Simulink |
| 5 | 18ME5205 | ROBOTICS AND ADVANCED CONCEPTS | CO1 | Perform Velocity and Static analysis of Manipulators |
| | | | CO2 | Formulation of equation of motions by computer simulations |
| | | | CO3 | Apply the Planning and control methods for robots |
| | | | CO4 | Modeling and controlling of flexible manipulators |
| 6 | 18ME5206 | CONTROL OF MECHATRONICS SYSTEMS | CO1 | Understanding the basic concepts of Modeling, Testing in terms of time domain and frequency domain |
| | | | CO2 | Analyze the basic designing concepts of Modern and optimal controllers such as state feedback and state observers. |
| | | | CO3 | Analyze the basic designing concepts of Digital controller for digital systems |
| | | | CO4 | Analyze the basic designing concepts of Non-linear controllers for non-linear systems |
| 7 | 18ME5207 | MECHATRONICS PRODUCT DESIGN | CO1 | Identify appropriate sensors, identify appropriate actuation system for a given application. |
| | | | CO2 | Identify appropriate microcontroller for a given application and to build a mathematical Model of system for evaluating open loop system performance and behavior. |
| | | | CO3 | Suggest an appropriate closed loop control strategy to attain the desired system behavior. |
| | | | CO4 | Suggest a Mechatronic product design for a given application and evaluate its performance. |
| | | | CO1 | To understand concept of accuracy, errors & its causes. |
| | | | CO2 | To know about geometrical dimensioning and tolerance |


Dr. A. SRINIVAS
PROFESSOR & HEAD
 Department of Mechanical Engineering
 KL (Deemed to be University)
 Vaddeswaram - 522 502

| | | | | |
|----|----------|---|-----|---|
| 8 | 18ME5208 | PRECISION ENGINEERING | CO3 | To understand concept of surface roughness and learn methods to improve surface finish. |
| | | | CO4 | To understand precision engineering methods |
| 9 | 18ME51A1 | SIGNAL PROCESSING IN MECHATRONIC SYSTEMS | CO1 | Analyze time signals, Discrete systems |
| | | | CO2 | Analyze Frequency filters and phase systems |
| | | | CO3 | Design FIR and IIR filter, bilinear transformation, and frequency transformations |
| | | | CO4 | Apply DSP to speech, and Radar signal processing |
| 10 | 18ME51A2 | MEMS & NEMS | CO1 | Introduction to MEMS and Microelectronic technologies used For MEMS |
| | | | CO2 | Microsensors & MEMS applications in Biological, Chemical and Acoustic field. |
| | | | CO3 | Introduction to MEMS based nanotechnology |
| | | | CO4 | NEMS physics and NEMS architecture |
| 11 | 18ME51A3 | VEHICLE DYNAMICS AND MULTI-BODY SYSTEMS | CO1 | Understand the concept of vehicle dynamics and analyze various parameters affecting it |
| | | | CO2 | Analyze the effect of aerodynamics and braking systems on the performance of vehicle |
| | | | CO3 | Analyze the steering systems ns suspension system effect on the performance of vehicle |
| | | | CO4 | Apply various mathematical models to understand the dynamics of Multi-body systems |
| 12 | 18ME51B1 | EMERGING SMART MATERIALS FOR MECHATRONIC APPLICATIONS | CO1 | Study of Smart materials and their application for sensing and actuation, Mechatronics aspects |
| | | | CO2 | Understand the principle of Piezoelectricity and piezoelectric materials, Constitutive equations, actuator types and Controls for precise positioning and scanning. |
| | | | CO3 | Understand the Basics of Ionic polymer metal composites (IPMC), Conductivity, Carbon nanotubes, Dielectric elastomers, Design & control issues and Applications of EAP (electro active polymers). |
| | | | CO4 | Understand the magnetic properties of materials, magnetostriction: constitutive equations, types, design & control of magneto strictive actuators. Comparative analysis of different smart materials. |
| 13 | 18ME51B2 | INTELLIGENT VISUAL SURVEILLANCE | CO1 | Apply basics of image processing to understand the video compression standards |
| | | | CO2 | Apply the basics of image processing to analyze various object detection techniques |
| | | | CO3 | Apply the Muti-object tracking method to understand human activity recognition |
| | | | CO4 | Apply the concept of networking to collaborate with camera |


Dr. A. SRINATH
PROFESSOR & HEAD
Department of Mechanical Engineering,
KL (Deemed to be University)
Vaddeswaram - 522 502

| | | | | |
|----|----------|--|-----|--|
| 14 | 18ME51B3 | MICROPROCESSORS AND EMBEDDED SYSTEMS | CO1 | Understand the fundamentals of embedded applications |
| | | | CO2 | Architectural understanding of processors through interfacing (8086) |
| | | | CO3 | Programming model of microcontroller(8051 family) |
| | | | CO4 | Interfacing and programming applications using microcontrollers |
| 15 | 18ME52C1 | COMPUTATIONAL FLUID DYNAMICS | CO1 | Understand the fundamentals of CFD and deriving governing equations |
| | | | CO2 | Apply different CFD techniques to diffusion problems |
| | | | CO3 | Solving convection-diffusion problems and N-S equations. |
| | | | CO4 | Understand numerical grid generation and apply Lattice-Boltzmann methods to complex flows |
| 16 | 18ME52C2 | NONLINEAR OPTIMIZATION | CO1 | Categorize convexity and non-convexity problems |
| | | | CO2 | Apply goal programming methods to solve models |
| | | | CO3 | solve problems with positive coefficients using separable and geometric programming |
| | | | CO4 | Implement search techniques to solve programming problems |
| 18 | 18ME52D1 | INDUSTRIAL AUTOMATION | CO1 | Apply principles of automation towards material handling and analyze their performance. |
| | | | CO2 | Analyze performance of storage systems and product flow in different GT methods and cellular manufacturing. |
| | | | CO3 | Application and analysis of transfer line without internal storage and describe Inspection Technology |
| | | | CO4 | Describe different manufacturing supporting systems. |
| 19 | 18ME52D2 | FUZZY SETS AND ARTIFICIAL INTELLIGENCE | CO1 | Understanding various concepts Fuzzy Logic System |
| | | | CO2 | Application of fuzzy Sets in Management, Medical and Engineering Fields. |
| | | | CO3 | Introduction to AI, Understand the basic concepts of Artificial Intelligence using various search Techniques |
| | | | CO4 | Neuro Fuzzy Approaches and Applications of AI in various Domains |



Professor I/C Academics



HOD-ME

Dr. A. SRINATH
PROFESSOR & HEAD

Department of Mechanical Engineering
KL (Deemed to be University)
Vaddeswaram - 522 502